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AUS9-2001-0094-US1

PATENT

WHAT IS CLAIMED IS:

1	1.	A depth cue method comprising the steps of:
2		scanning a depth map corresponding to an image, in response to user input; and
3		outputting a nonvisual cue corresponding to a depth value in said depth map, for
4	each j	pixel scanned.

- 2. The method of claim 1 wherein said nonvisual cue is selected from the group consisting of auditory cues and tactile cues.
 - 3. The method of claim 1 wherein said depth map is received in response to a web page containing said image.
 - 4. The method of claim 3 further comprising the step of, if no depth map is received in response to said web page containing said image, generating said depth map.
 - 5. The method of claim 4 wherein said step of generating said depth map comprises: performing a depth analysis of a set of images associated with said image, said set of images operable for extracting depth information therefrom.; and assigning a depth value corresponding to said depth information for each pixel corresponding to said image.
- 6. The method of claim 5 wherein said set of images associated with said image is

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AUS9-2001-0094-US1 PATENT

1	selec	selected from the group consisting of a stereographic pair including said image and a	
2	plurality of images operable for displaying motion.		
1	7.	The method of claim 5 wherein said step of generating said depth map further	
2	comprises the steps of:		
3		setting each depth value in a data structure to form said depth map; and	
4		outputting said data structure.	

corresponding to said image.

AUS9-2001-0094-US1 PATENT

1	8.	A computer program product embodied in a tangible storage medium, the
2	prog	ram product for accessing graphical data, the program product including a program
3	of ins	structions for performing the steps of:
4		scanning a depth map corresponding to an image, in response to user input; and
5		outputting a nonvisual cue corresponding to a depth value in said depth map, for
6	each	pixel scanned.
1	9.	The program product of claim 8 wherein said nonvisual cue is selected from the
2	group	o consisting of auditory cues and tactile cues.
1	10.	The program product of claim 8 wherein said depth map is received in response
2	to a v	veb page containing said image.
1	11.	The program product of claim 10 further comprising programming for performing
2	the s	tep of, if no depth map is received in response to said web page containing said
3	imag	e, generating said depth map.
1	12.	The method of claim 11 wherein said programming for performing step of
2	gener	rating said depth map comprises programming for performing the steps of:
3		performing a depth analysis of a set of images associated with said image, said
4	set of	f images operable for extracting depth information therefrom.; and
5		assigning a depth value corresponding to said depth information for each pixel

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AUS9-2001-0094-US1 PATENT

13.	The program product of claim 12 wherein said set of images associated with said
image	is selected from the group consisting of a stereographic pair including said image
and a	plurality of images operable for displaying motion.

- 14. The program product of claim 12 wherein said programming for performing step of generating said depth map further comprises programming for performing the steps of:
 - setting each depth value in a data structure to form said depth map; and outputting said data structure.

AUS9-2001-0094-US1

PATENT

1	15.	A data processing system comprising:	
2		circuitry operable for scanning a depth map corresponding to an image, in	
3	respon	response to user input; and	
4		outputting a nonvisual cue corresponding to a depth value in said depth map, for	
5	each p	pixel scanned.	
1	16.	The system of claim 15 wherein said nonvisual cue is selected from the group	
2	consis	sting of auditory cues and tactile cues.	
1	17.	The system of claim 15 wherein said depth map is received in response to a web	
2	page o	containing said image.	
1	18.	The system of claim 17 further comprising circuitry operable for, if no depth map	
2	is rec	eived in response to said web page containing said image, generating said depth	
3	map.		
1	19.	The system of claim 18 wherein said circuitry operable for generating said depth	
2	map c	comprises:	
3		circuitry operable for performing a depth analysis of a set of images associated	
4	with s	aid image, said set of images operable for extracting depth information therefrom.;	
5	and		
6		circuitry operable for assigning a depth value corresponding to said depth	

information for each pixel corresponding to said image.

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AUS9-2001-0094-US1 PATENT

The system of claim 19 wherein said set of images associated with said image is

2	selected from the group consisting of a stereographic pair including said image and a	
3	plurality of images operable for displaying motion.	
1	21. The system of claim 17 wherein said circuitry operable for generating said depth	
2	map further comprises:	
3	circuitry operable for setting each depth value in a data structure to form said	
4	depth map; and	